**ROS2 Scientific Paper Edition Log**

**File Location：**<https://www.overleaf.com/project/680a65ec4cd4e0e1aa5d86ac>

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| --- | --- | --- | --- |
| Chapter/Section/Task | Creator | Editor | Notes |
| Abstract | Samuel |  | 1st Version |
|  | Sheng-Hsiang | Revised background  Added test verification, conclusion |
| Introduction | Samuel |  | 1st Version |
|  | Sheng-Hsiang | Separate into two sections (Motivation & ROS2)  Added new section explaining background,  platform needs, and reason for using ROS2. |
| Challenges & Issues | Samuel |  | 1st Version |
|  | Sheng-Hsiang | Clarified challenges with ROS2 installation on  non-Linux systems  Added test experience. |
| System Architecture | Samuel |  | 1st Version |
| Implementation | Samuel |  | 1st Version |
|  |  | Sheng-Hsiang | Revised paragraph “MATLAB Integration”  Added ROS2 on MATLAB with iOS |
| Experiment and Results | Samuel |  | 1st Version |
|  |  | Sheng-Hsiang | Added “Image Subscription and Visualization in iOS” |
| Conclusion & Outlook | Samuel |  | 1st Version |
| Figures / Diagrams | Samuel |  | 1st Version |
|  | Sheng-Hsiang | Added Image for iOS |
|  |  |  |  |